

---

## Vehicle Electrification System Standards

### V. Phase Drive Motors and Generators

---

## V.d Permanent Magnet Electric Machines

### Description:

3-Phase electric machines are the central component of an electric powertrain system and it provides propulsion and generated electrical power to HEV, PHEV, and BEV architectures. Understanding the construction, operation, failure modes, and diagnostic processes for Permanent Magnet electric machines is foundational in preparing students for a service career in the electrification service space.

---

### Outcome (Goal):

Students will be able to describe and illustrate how Permanent magnet electric machines operate in all modes of vehicle operation; describe how PM electric machines are constructed; analyze and evaluate the condition of PM electric machine technologies by using various diagnostic techniques and tools..

---

### Objective:

Students shall be able to:

1. Identify and Define IM and PM electric machine internal components
  2. Describe how PM electric machines are constructed
  3. Explain the concepts of how PM machine Lead, Lag, and Zero Torque is produced
  4. Compare and contrast Constant Torque and Constant Power
  5. Demonstrate how to analyze and evaluate the condition of IM using a serial data (scan) tool, oscilloscope, milliohmmeter, insulation tester, and specialized analysis testers.
- 



**Task:**

Students will be able to describe how vehicle PM electric machine propulsion, regenerative braking, and coasting modes; identify powertrain architectures and powertrain components; perform testing and analysis using live vehicles or test stands; define the term power density in the provided pictures or diagrams, using OEM vehicle service, component supplier information, and DOE/NREL/INL/ANL vehicle electrification website information while using proper technical terminology, acronyms, and definitions.

Construction and Manufacturing	
Housing	
Stator Core	<ul style="list-style-type: none"> <li>Laminations</li> <li>Lamination Slot Configurations</li> <li>Slot Fill</li> <li>Round Wire – Random Distributed Windings</li> <li>Hairpin Distributed Windings</li> <li>Concentrated Windings</li> <li>Series and Parallel Winding Configuration</li> <li>Number of Poles vs Torque and Speed</li> <li>Stator End Turn Cooling</li> <li>Stator Temp Sensor</li> </ul>
Rotor	<ul style="list-style-type: none"> <li>Rotor Diameter - as it relates to Torque</li> <li>Rotor Length - as it relates to Torque</li> <li>Interior Magnet Rotor               <ul style="list-style-type: none"> <li>“V” Shape</li> <li>Double “V” Shape</li> <li>Skewed</li> <li>Rare Earth</li> <li>Ferrite</li> <li>Halbach Array</li> <li>Rotor Shaft Bearings</li> <li>Rotor Shaft Currents</li> <li>PM Machine Spin Loss</li> </ul> </li> </ul>



<b>Traditional PM vs Reluctance Torque PM Machines</b>	
	Traditional PM Electric Machines
	Reluctance PM Machines
<b>Electric Machine Operating Regions</b>	
	Constant Torque
	Constant Power
<b>PM Machine Torque &amp; Speed Control Operation</b>	
	Concept of Sine Wave Lead and Lag
	Speed (rpm)
	Base Speed
	How Max rpm is Determined
Torque	
	Vector Lead
	Zero Lead-Lag
	Vector Lag
Software Flux Vector Tables	
	Flux Vector Table Control Strategy
	Flux Vector vs. Stator Current Control
<b>PM Machine Failure Modes</b>	
	Stator
	Rotor
	Bearings
<b>Diagnostics &amp; DTCs</b>	
<b>Servicing PM Electric Machines</b>	

To comment or offer suggestions on this standard, contact Ken Mays:

<b>Ken Mays</b>	<b>NEVTEX</b>
541-383-7753	<a href="mailto:kmays@cocc.edu">kmays@cocc.edu</a>

