

# Shape-changing micromachines

**Daniel López**

**Electrical Engineering and Computer Science**

**Materials Research Institute**

**Pennsylvania State University**

**[dlopez@psu.edu](mailto:dlopez@psu.edu)**

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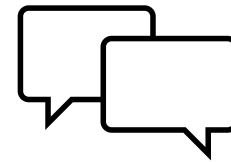
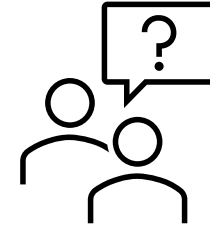
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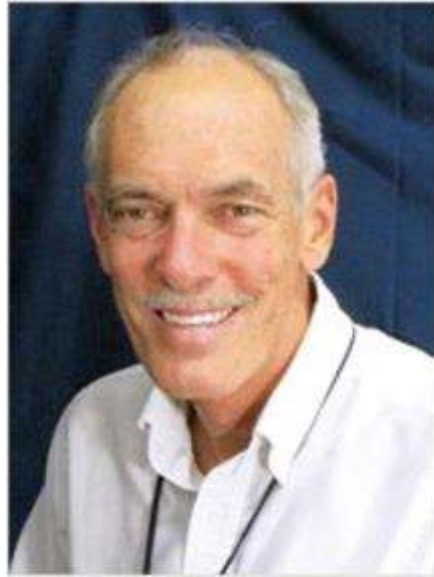


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Managing Director  
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Mike Lesiecki  
Co-PI  
Preparing  
Technicians for the  
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Daniel Lopez  
Liang Professor of  
Electrical Engineering  
and Computer  
Science  
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# Shape-changing micromachines

**Daniel López**

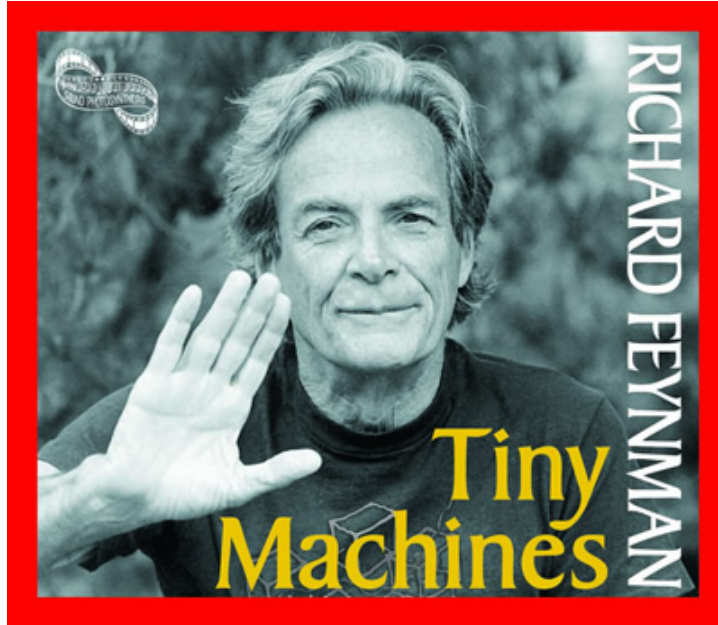
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# Miniaturized machines



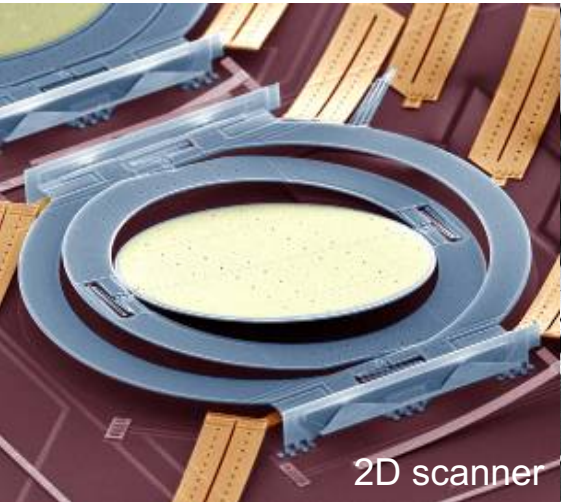
- Miniaturize information ✓
- Miniaturize computing ✓
- Miniaturize machines ✗

## Nanomachines: Nanoscale systems

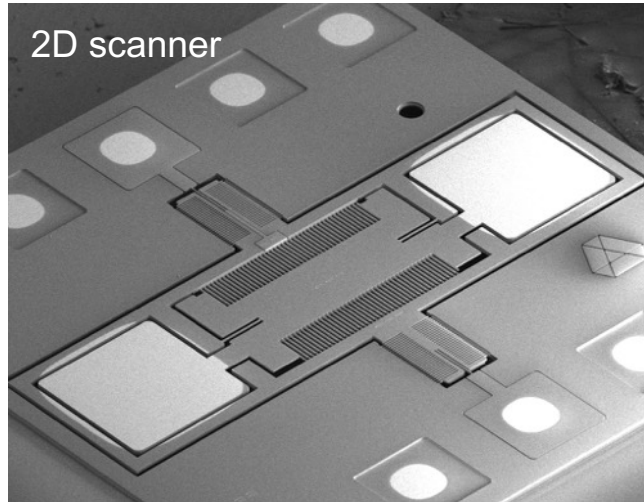
Anything that can gather information and manipulate environment at the micro and nano world.



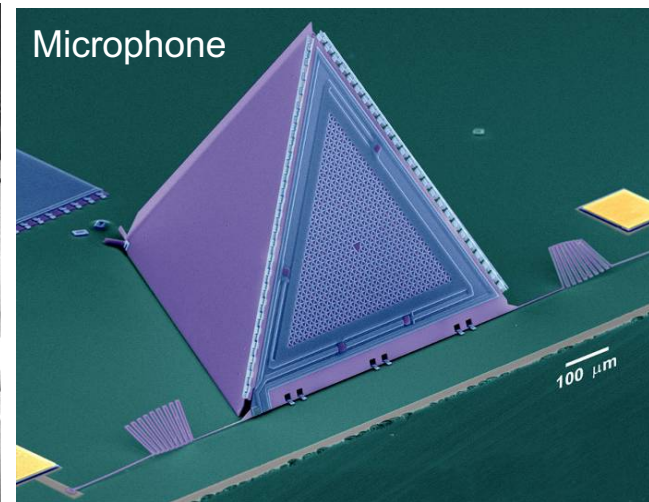
# Micro Electro Mechanical Systems technology



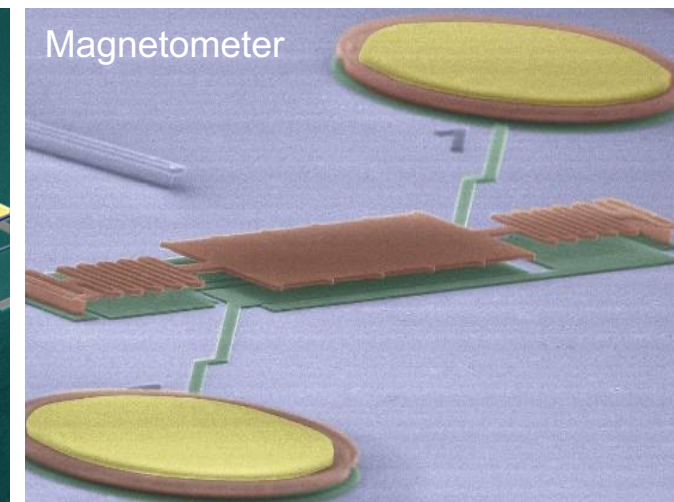
Bell Labs



ANL

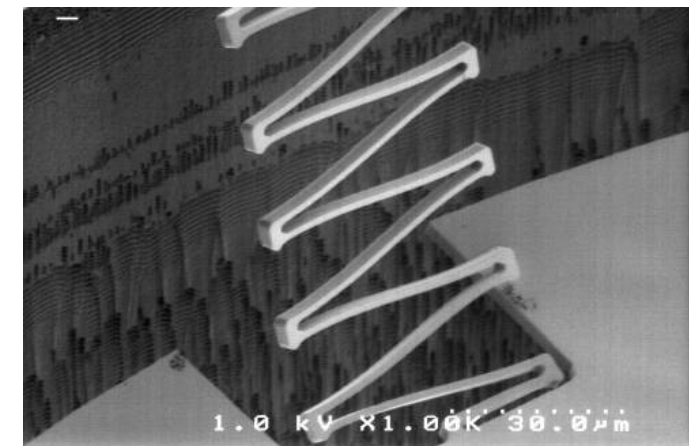
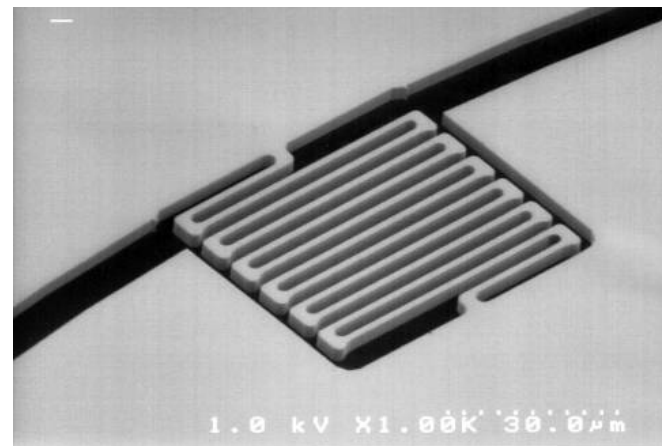


Bell Labs

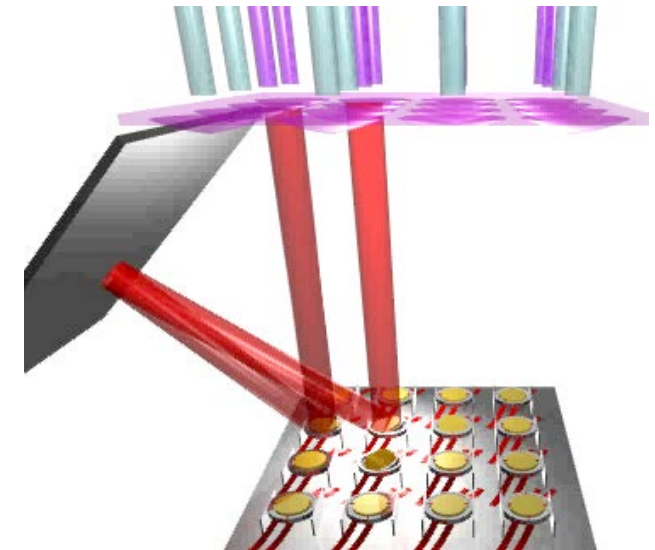
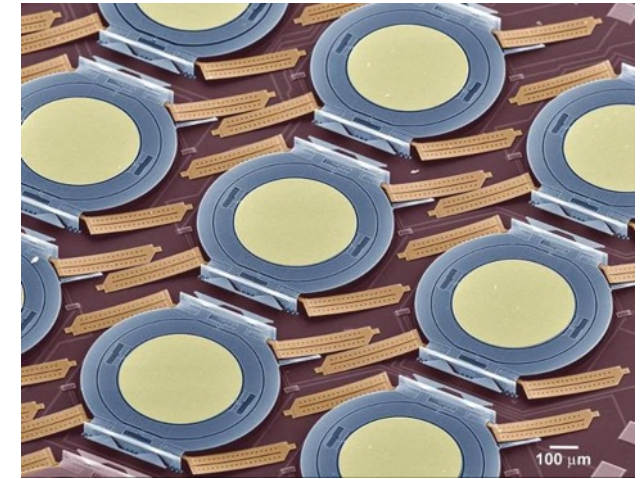


ANL

- Typical size: few  $\mu\text{m}$  to 100's  $\mu\text{m}$
- Well known materials and fabrication processes
  - Si is a well understood material
  - Easy to design, control and manipulate
  - Elasticity theory works well (Hooke's law)
- Applications: basic science to high-end products
- Hard environments: X-rays, accelerations,...



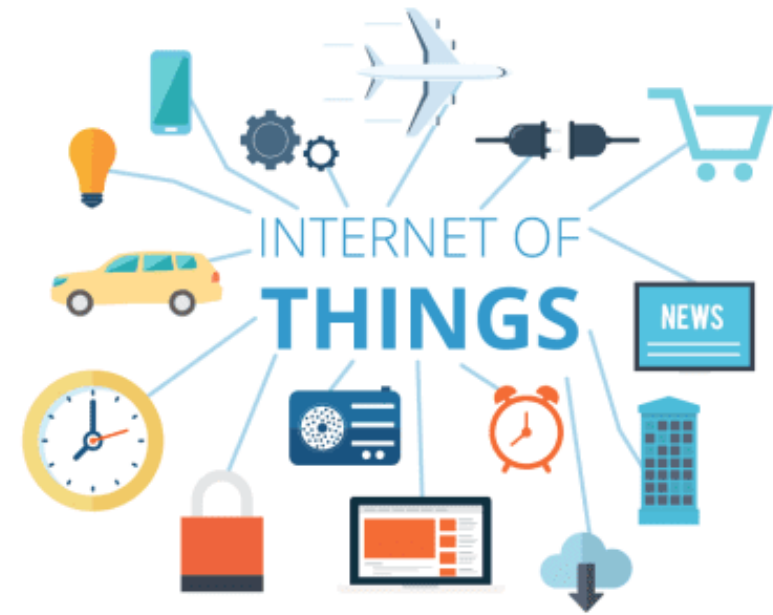
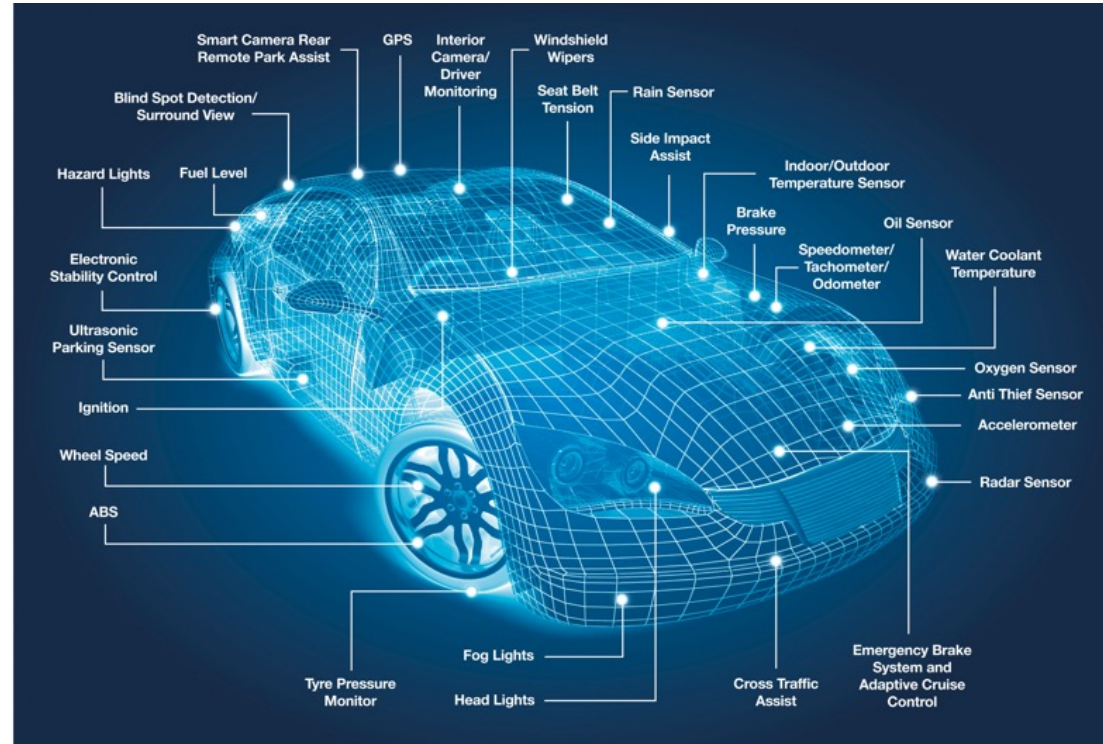
# MEMS for communications



Handle large amount of information: Big Data

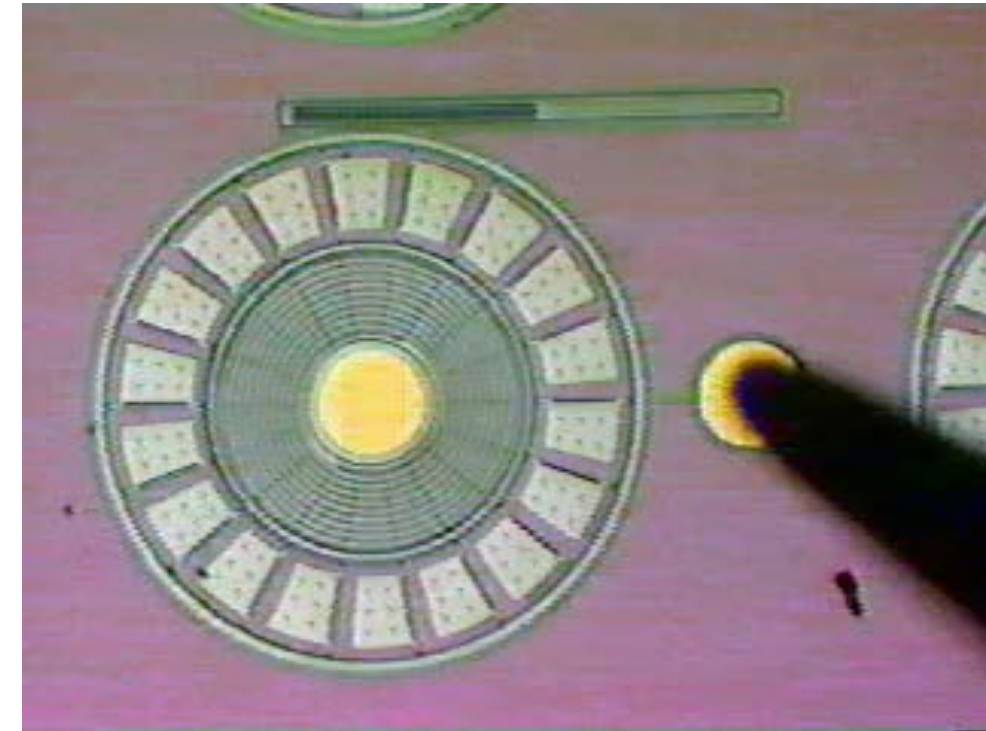
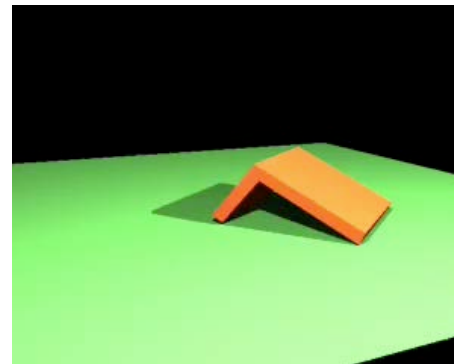
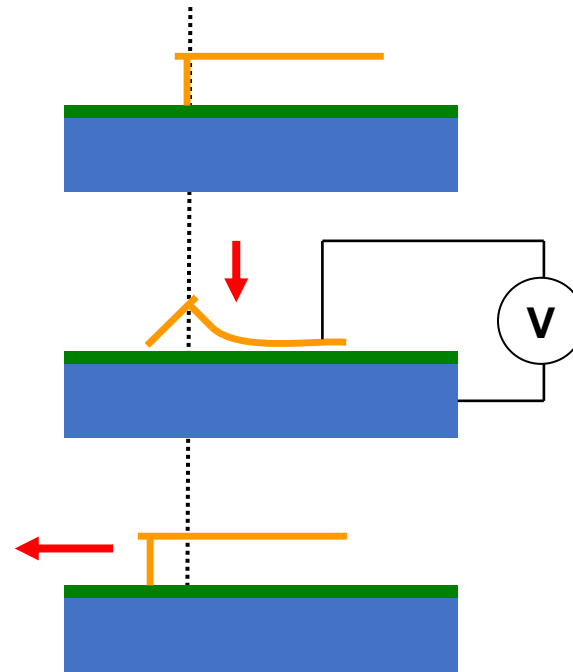
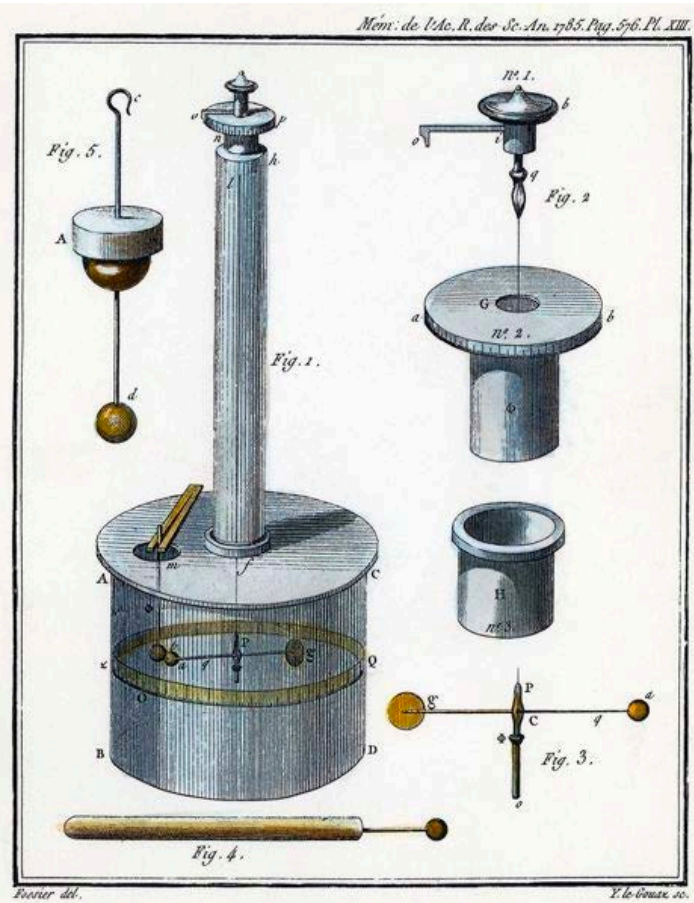


# Micromachines today



# MEMS technology today: actuation forces

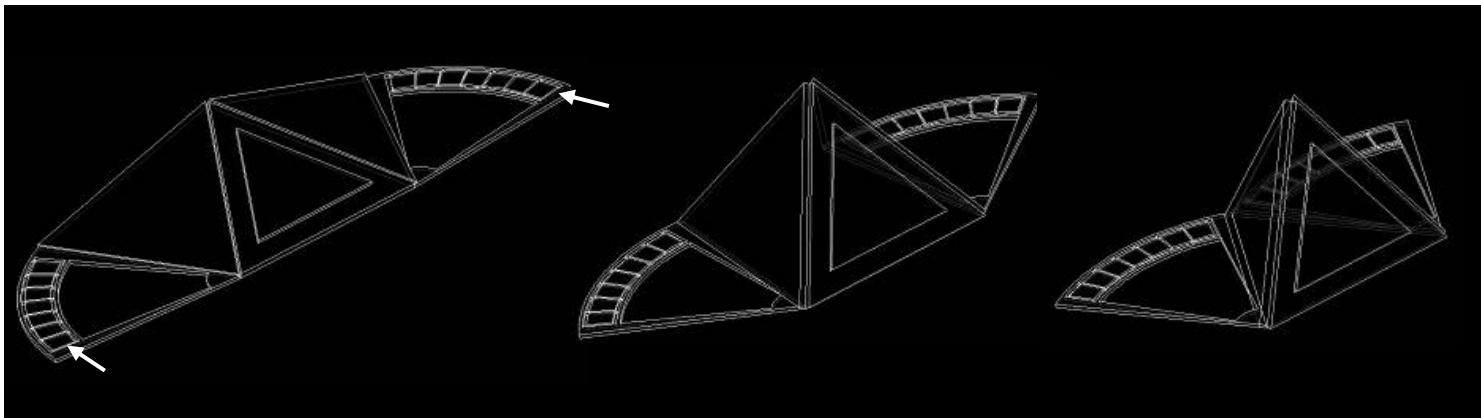
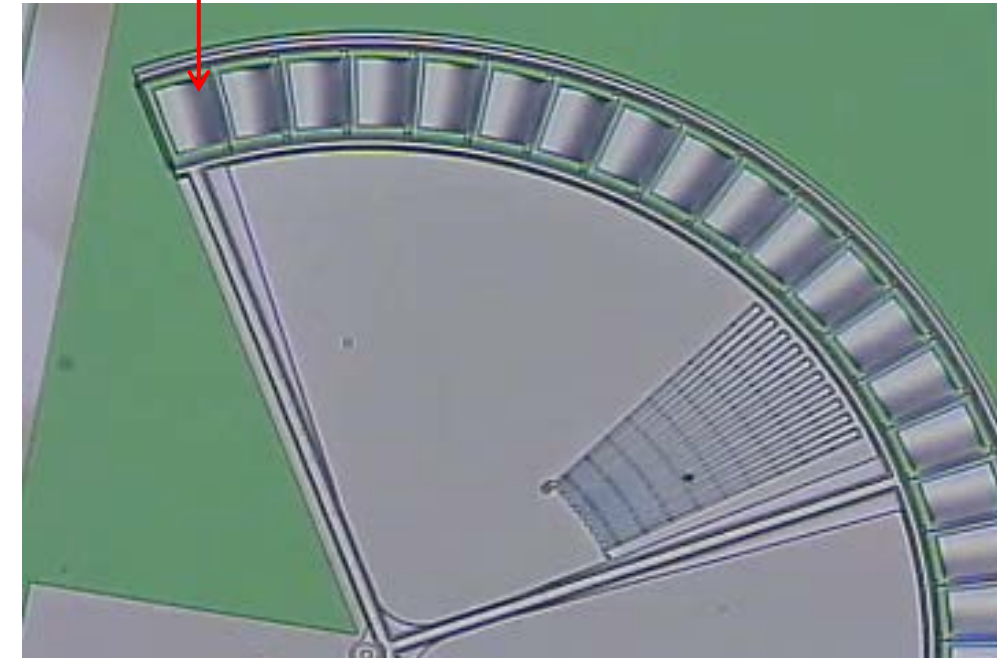
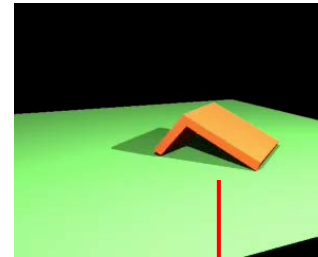
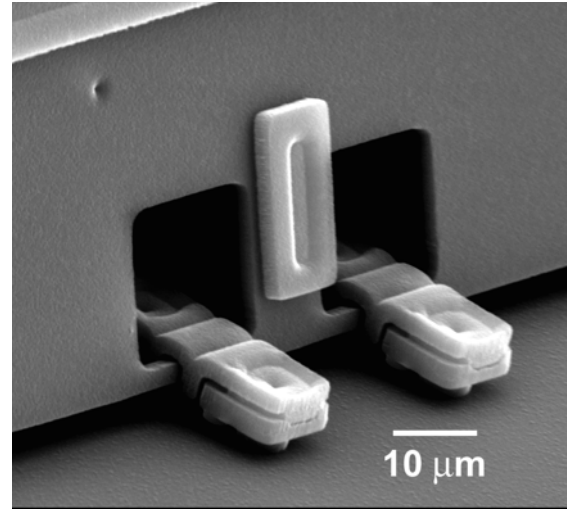
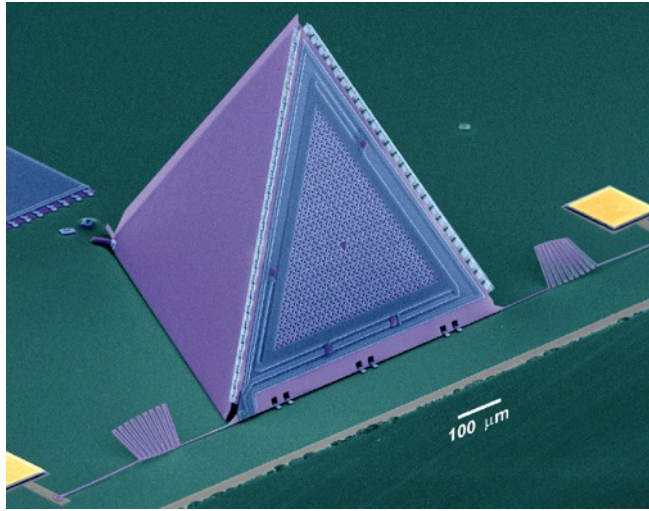
Coulomb balance - 1785



**Electrostatic forces vs. Mechanical deformation**



# MEMS technology today: 3D structures



Micro-machines can be used to assemble and build micro-machines

# Micromachines technology evolution

- Very large-scale integration of MEMS
- Intelligent micro-systems



# Very large-scale integration

One transistor



Few transistors

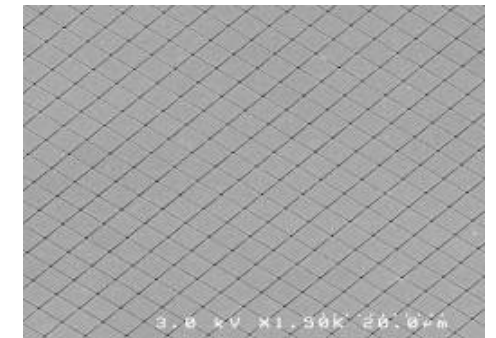
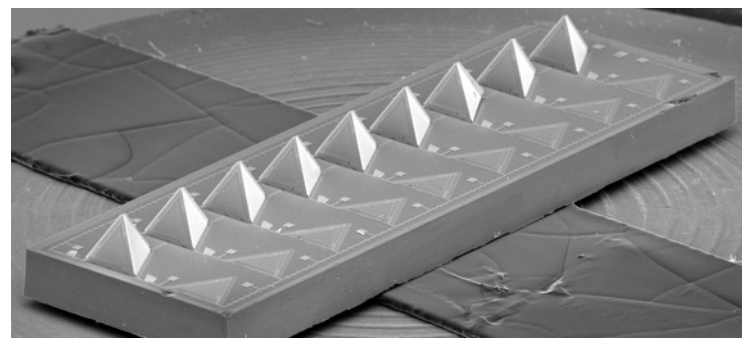
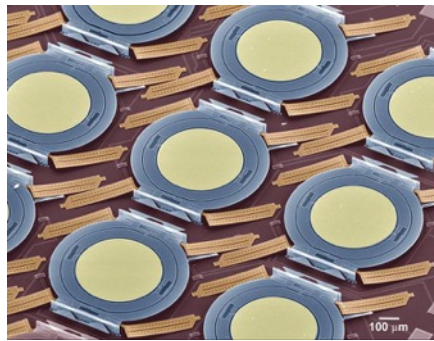
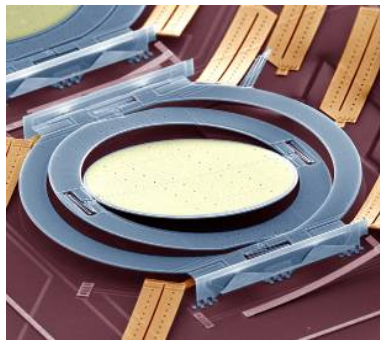
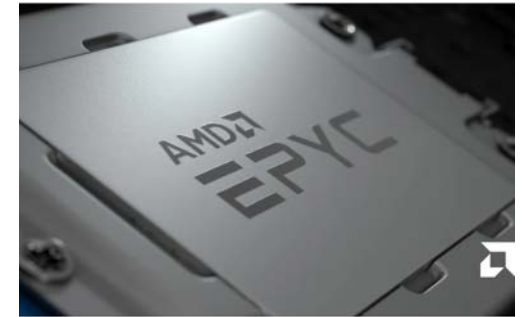


Few million transistors



High-end microprocessor ([AMD "Epyc"](#)) contains 40 billion transistors in a chip about 3 cm on a side.

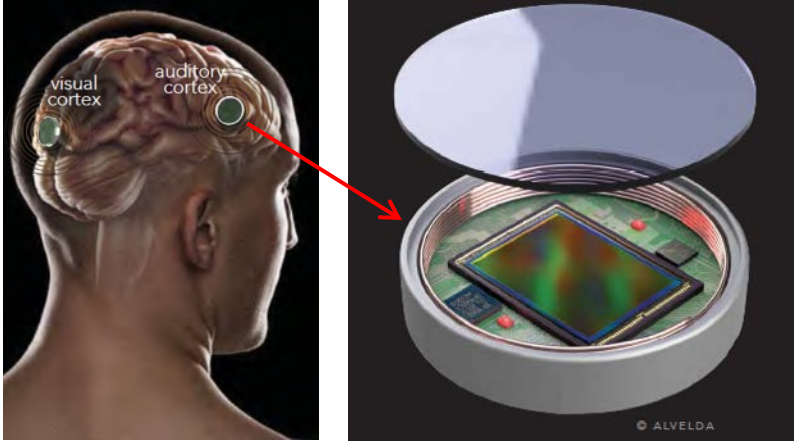
AMD EPYC™ 7002 Series Processors



Building the mechanical equivalent of a Pentium chip:  
giving arms to a microprocessor

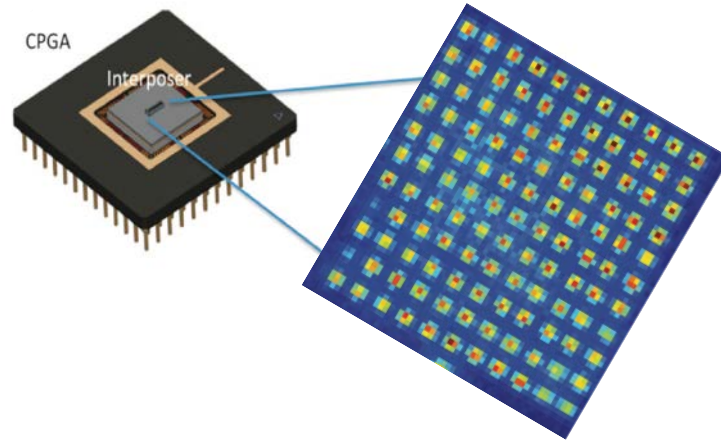
# MEMS-based Spatial Light Modulators

## Neural Engineering System Design (NESD)



Device that can read  $10^6$  neurons and write to  $10^5$  neurons

## Optimization with Noisy Intermediate-Scale Quantum devices (ONISQ)

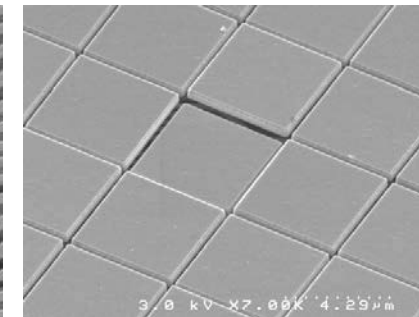
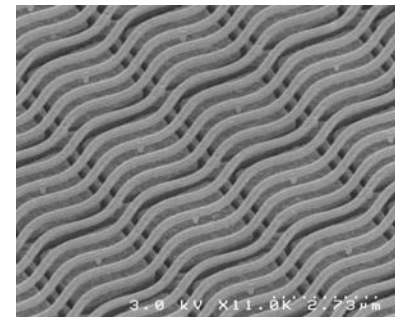
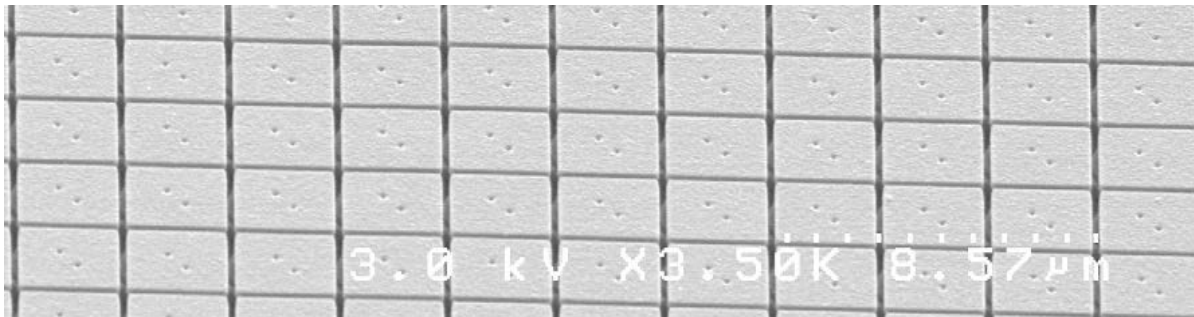


Trapping of neutral atom with parallel operation of gates and beam shaping at  $\mu\text{sec}$  speed

## Adaptive Laser Headlights

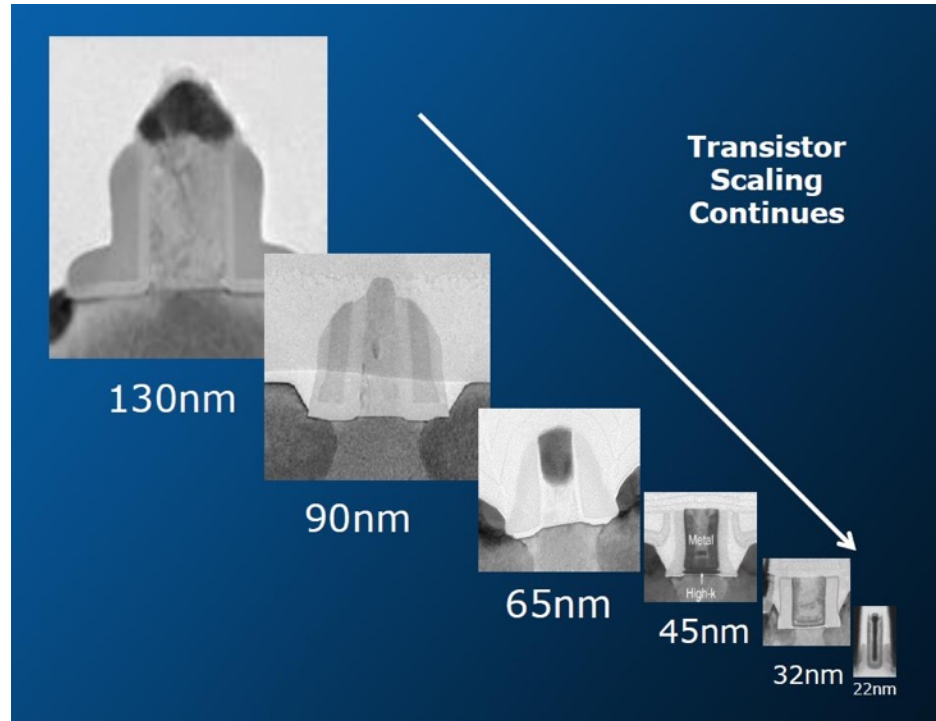


Active shaping of a vehicle's high beam

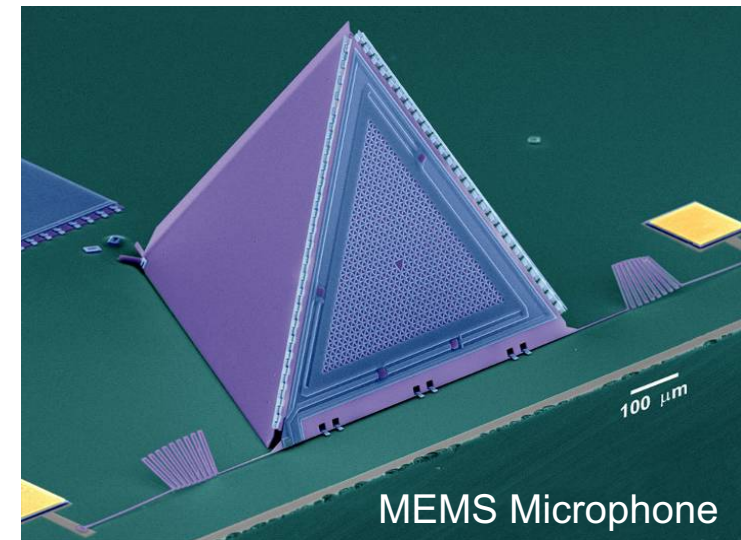
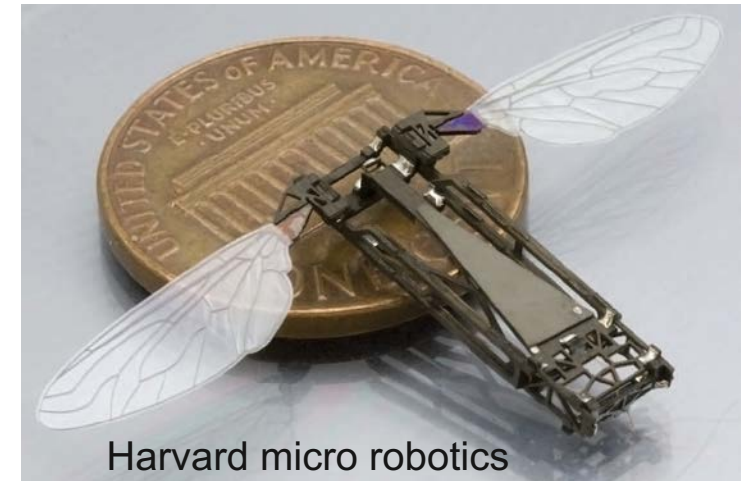




# From MEMS to NEMS

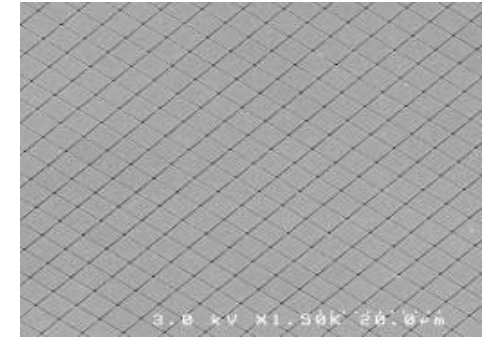
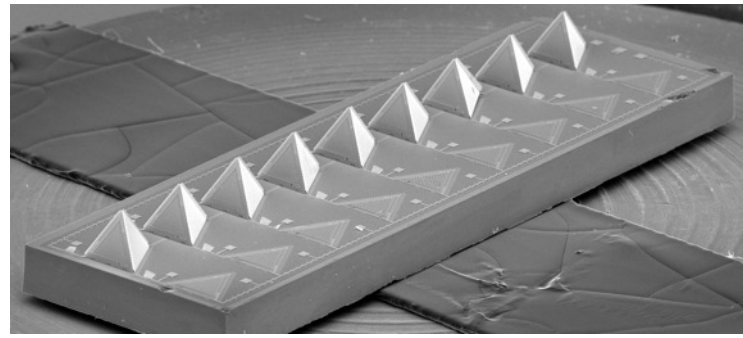
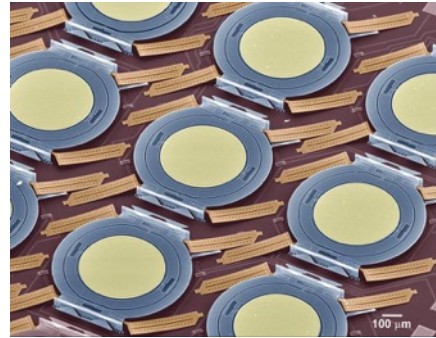
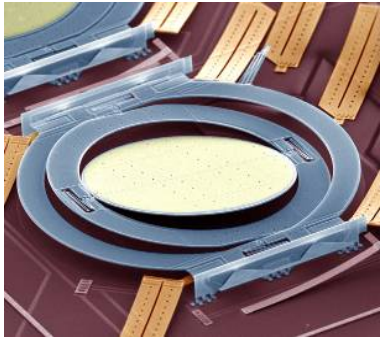


Scale invariant → Moore's Law



- NO Moore's law for nano-systems
- NOT scale invariant (physics is scale dependent)

# Micromachines technology evolution

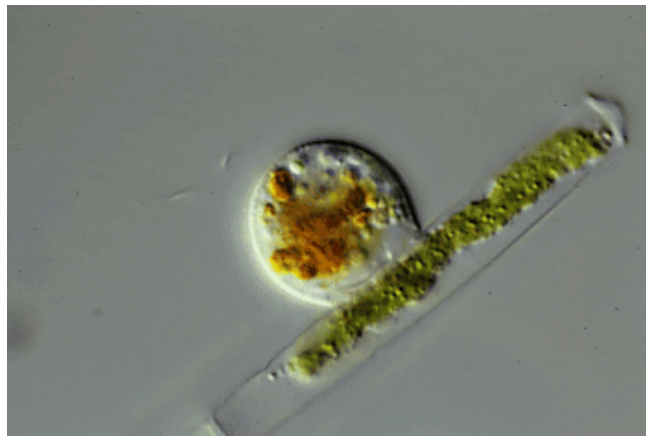
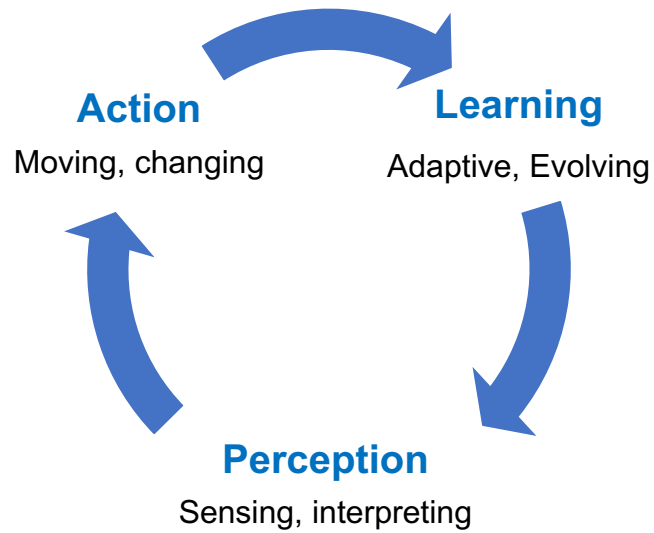


Intelligent micro-systems

Questions?



# Intelligent micro-systems



Cell-scale intelligence  
(perception, action and learning/adaptation)

## Physical Intelligence (PI)

*Encoding intelligence (perception, action & adaptation/learning) inside the physical body of a physical agent (structure, machine, robot, etc.)*

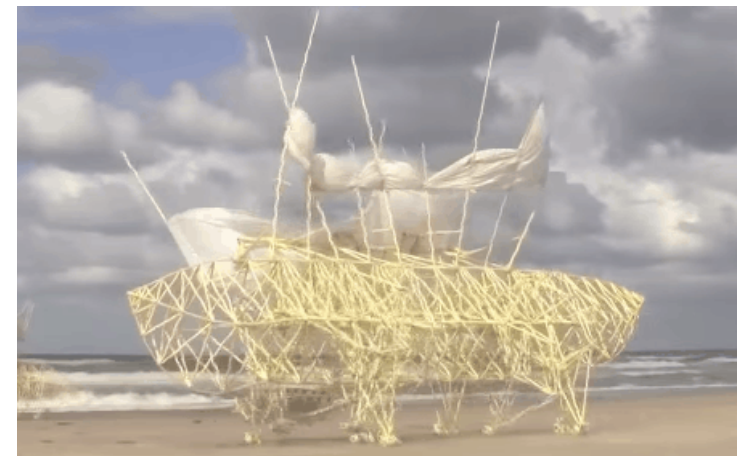
Physical intelligence versus neural Computational Intelligence

- Centimeter and larger scale: CI dominant
- Millimeter scale (limited on-board powering/actuation/computation):  $PI \approx CI$
- Microscale (no on-board powering/actuation/computation): PI only

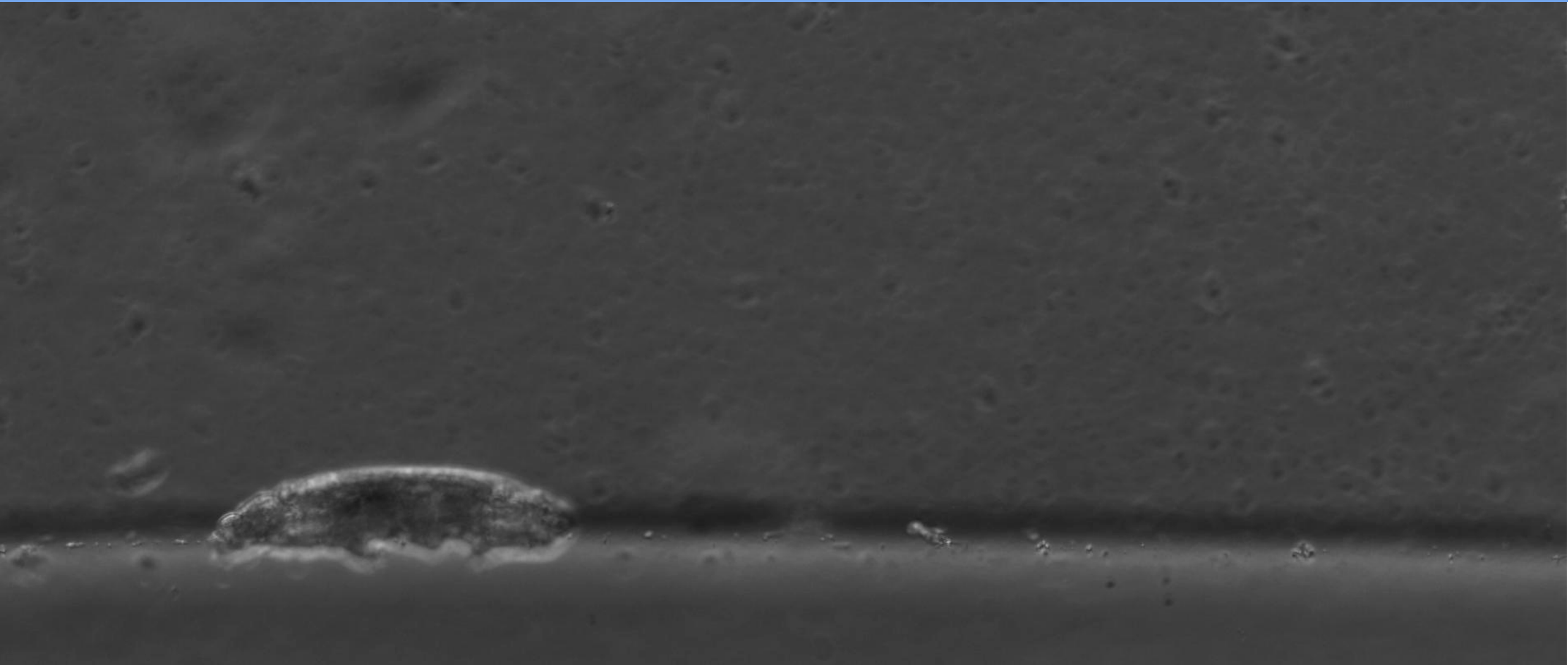
Metin Sitti - Max Planck Institute for Intelligent Systems



Theo Jansen

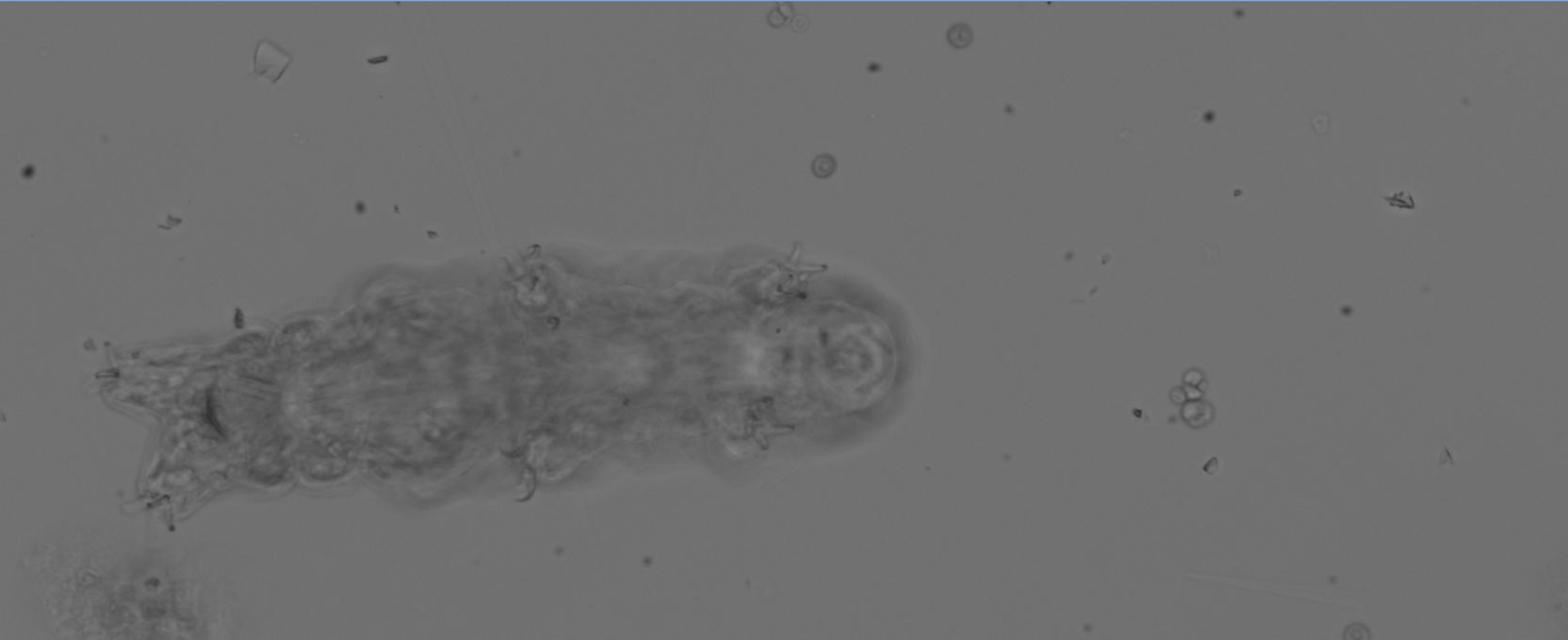


# Intelligent micro-systems



Tardigrades exhibit robust inter-limb coordination across walking speeds (bioRxiv – 3/20/21)- Daniel Cohen's group

# Intelligent micro-systems



Tardigrades exhibit robust inter-limb coordination across walking speeds (bioRxiv – 3/20/21)- Daniel Cohen's group

# Physical Intelligence

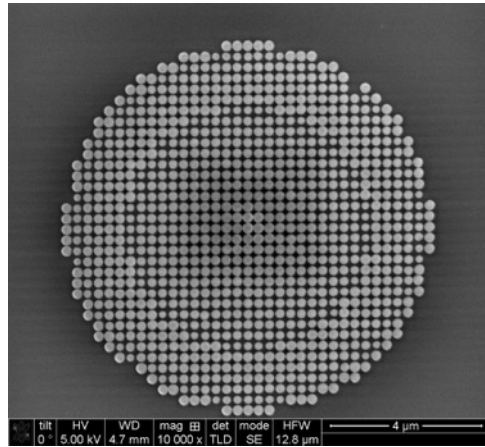
## How to create Physical Intelligence in Micro-systems?

- Physical self-adaptation to changing conditions
  - Reconfigurable morphology, stiffness, damping, color
- Self-sensing & self-reacting to external stimuli or forces
  - Light, temperature, flow,
- Encoding autonomous behavior by smart materials & interactions
  - Mechanical memory
  - Self-propulsion
  - Self-organization

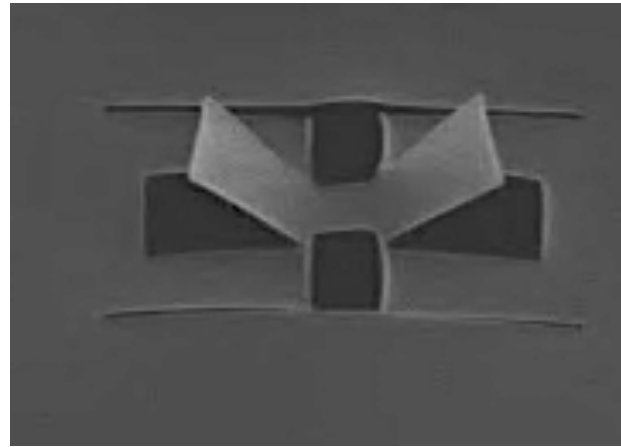


# A vision for intelligent microsystems

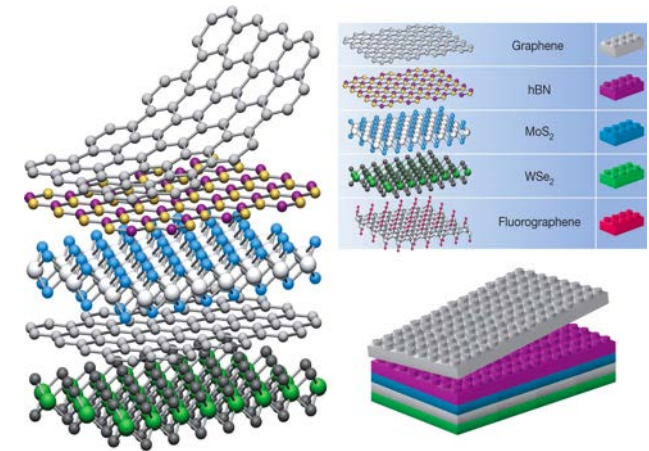
Flat optics



Kirigami nano-actuators

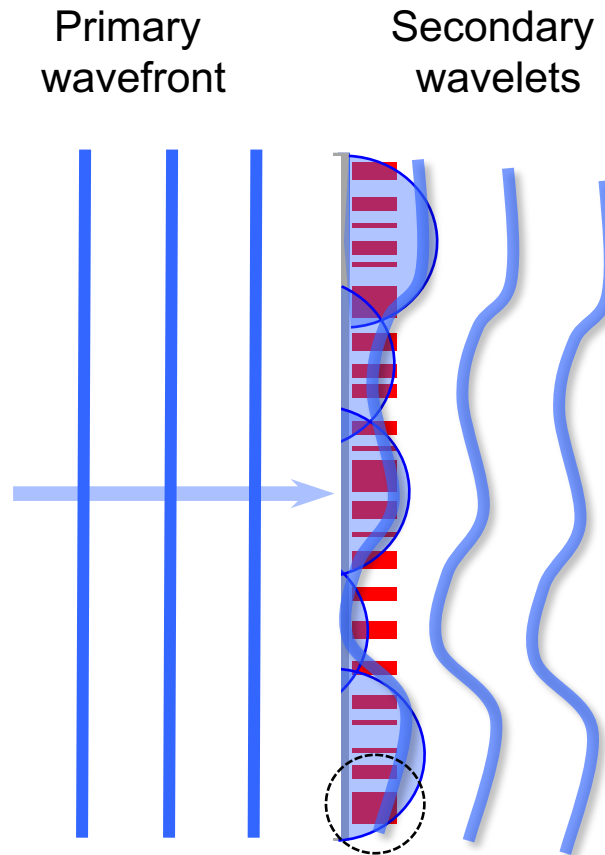
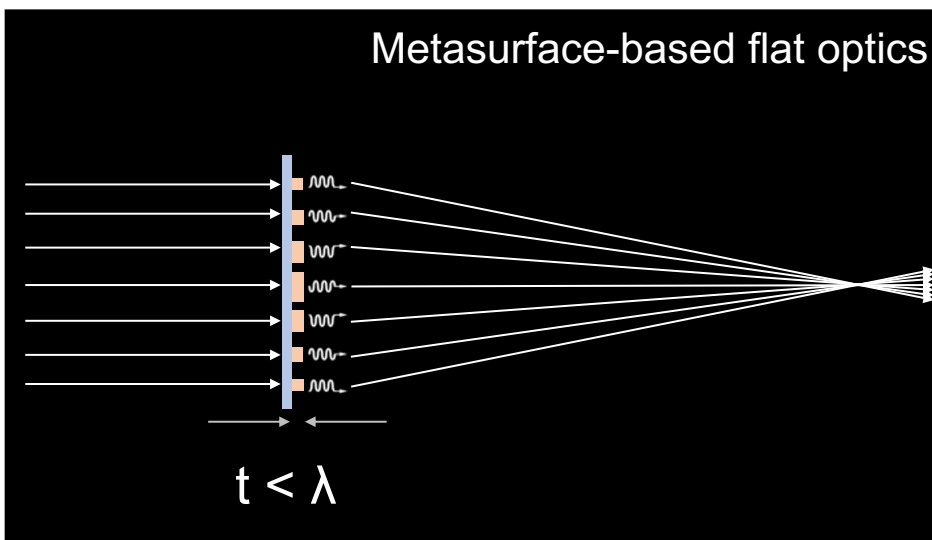
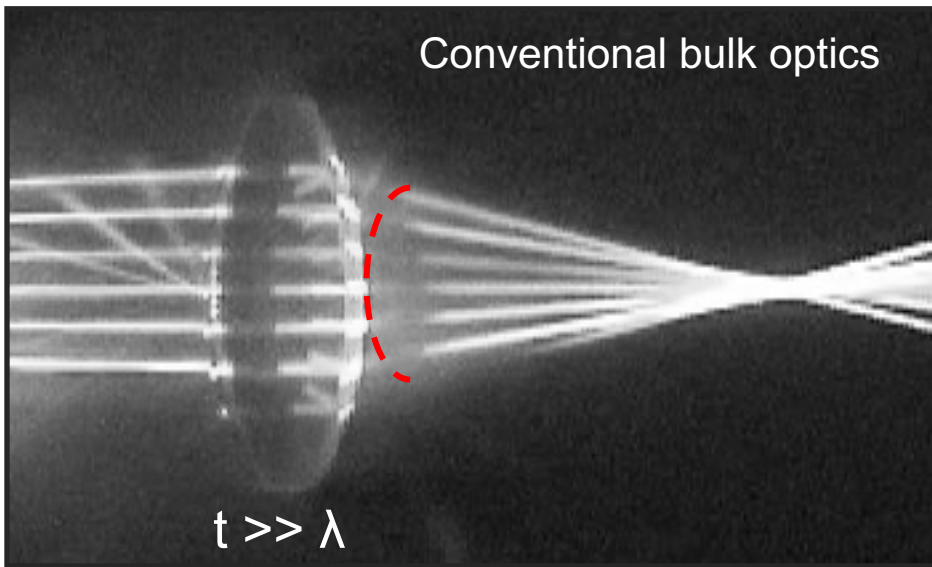


2D Electronics

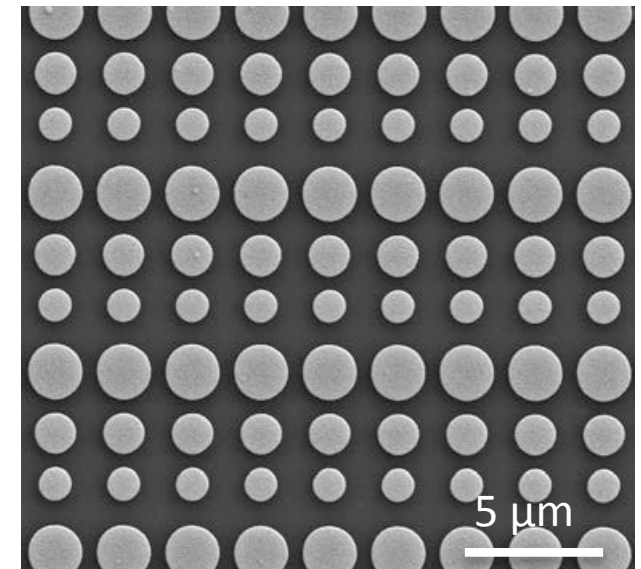


New paradigm for designing intelligent microsystems

# Metasurface-based flat optics

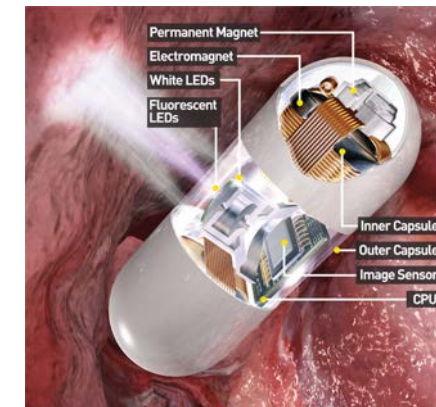
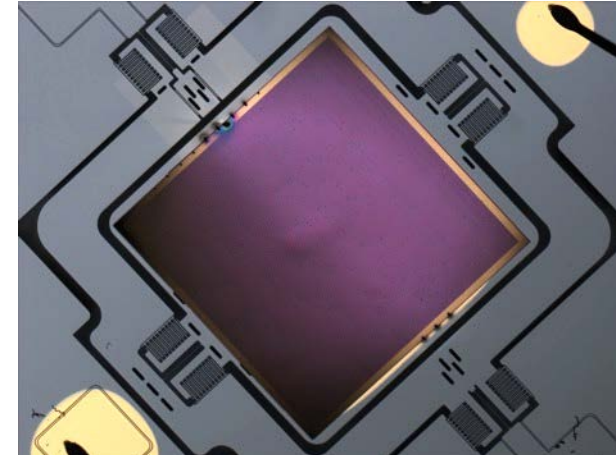
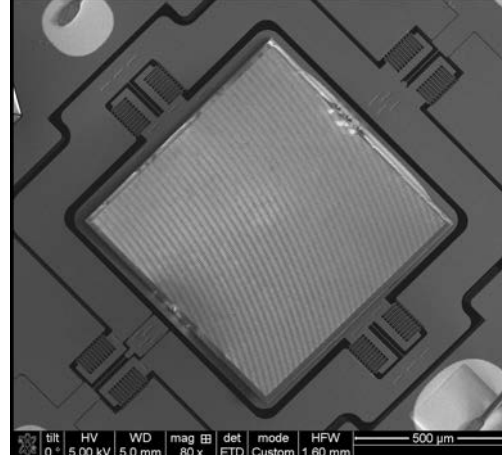
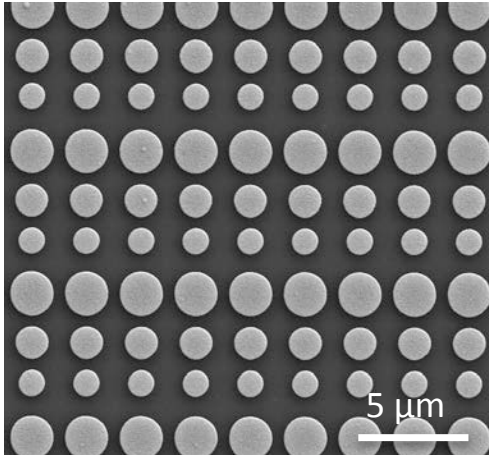


- **Straight-Forward Fabrication**
  - One mask level, cost effective
- **Compact**
  - Light weight
- **Unprecedented Control of Dispersion**
- **Overcome Limitations of Conventional Optics**
  - Aberrations, multifunctionality
- **CMOS compatible**



# Metasurfaces and MEMS

Incorporation of flat-optics onto MEMS scanners → Flat optical systems





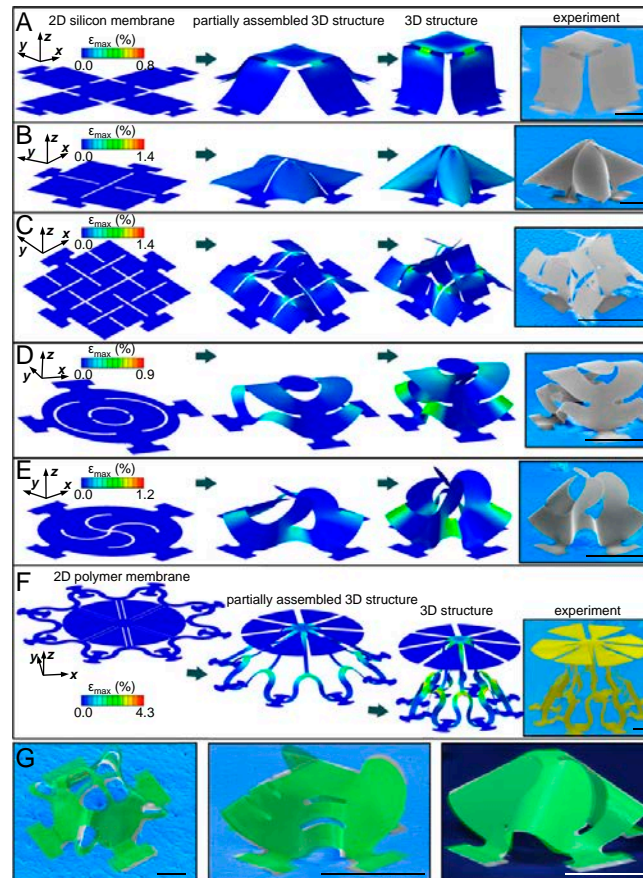
# Origami - Kirigami structures

Inspired by the ancient Japanese art of paper folding and cutting, and recent developments in modeling that allow inverse design of complex shapes from a single sheet of paper, Origami and Kirigami had emerged as a powerful strategy to transform 2D layouts into **scale invariant** 3D complex architectures that are difficult to achieve by conventional fabrication processes and additive manufacturing



## A mechanically driven form of Kirigami as a route to 3D mesostructures in micro/nanomembranes

Yihui Zhang<sup>a,1</sup>, Zheng Yan<sup>b,1</sup>, Kewang Nan<sup>c</sup>, Dongqing Xiao<sup>d</sup>, Yuhao Liu<sup>b</sup>, Haiwen Luan<sup>e</sup>, Haoran Fu<sup>e,f</sup>, Xizhu Wang<sup>b</sup>, Qinglin Yang<sup>b</sup>, Jiechen Wang<sup>b</sup>, Wen Ren<sup>g</sup>, Hongzhi Si<sup>b</sup>, Fei Liu<sup>a</sup>, Lihen Yang<sup>b</sup>, Hejun Li<sup>g</sup>, Juntong Wang<sup>c</sup>, Xuelin Guo<sup>b</sup>, Hongying Luo<sup>a,h</sup>, Liang Wang<sup>e,i</sup>, Yonggang Huang<sup>b,2</sup>, and John A. Rogers<sup>b,d,j,2</sup>

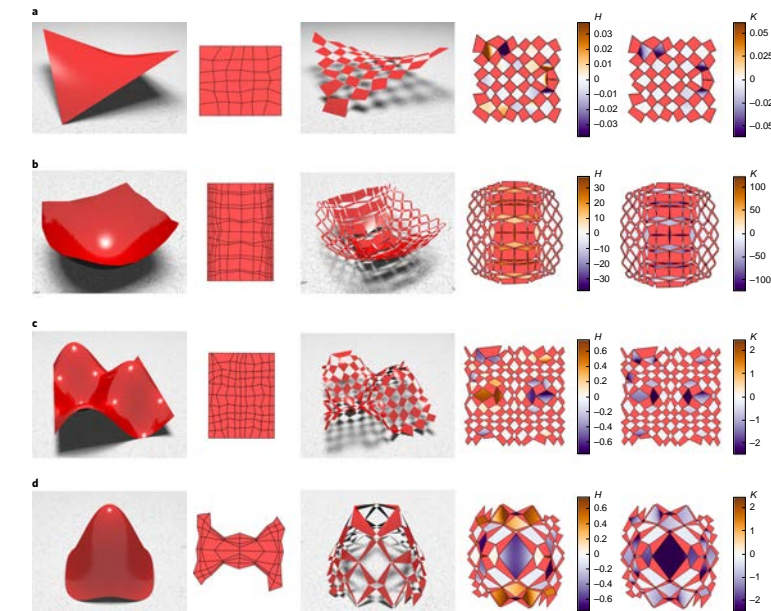


John Rogers (NU)



## Programming shape using kirigami tessellations

Gary P. T. Choi<sup>1</sup>, Levi H. Dudte<sup>1</sup> and L. Mahadevan<sup>1,2,3\*</sup>



**Fig. 4 | Generalized kirigami patterns for three-dimensional surface fitting.** **a-d.** The target surfaces are a hyperbolic paraboloid (with negative curvature) (**a**), a paraboloid (with positive curvature) (**b**), a periodic patch of an egg-carton shape (**c**) and a bivariate Gaussian (**d**). Columns: the target surfaces (leftmost), the generalized kirigami patterns, the deployed configurations of the patterns that fit the target surfaces, the top views of the deployed patterns with the holes coloured with the approximated mean curvature  $H$  and the top views of the deployed patterns with the holes coloured with the approximated Gauss curvature  $K$  (rightmost).

L. Mahadevan (Harvard)  
K. Bertoldi, D. Nelson



# Origami - Kirigami structures

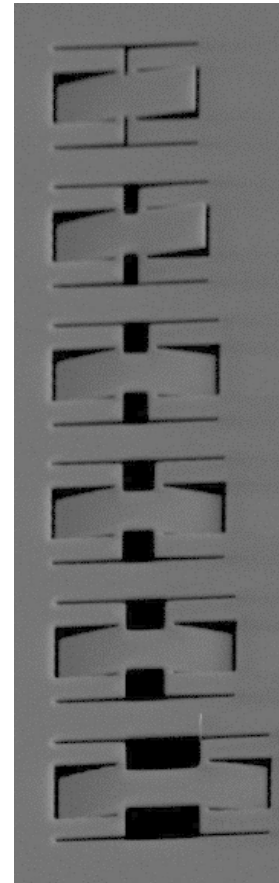
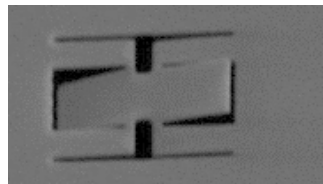
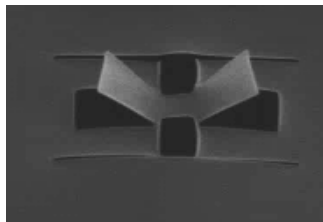
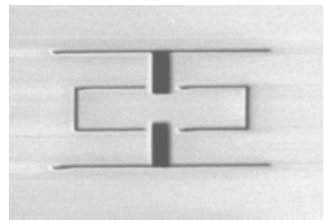
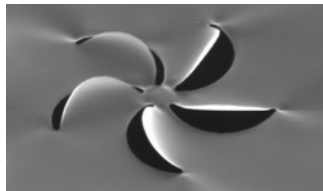
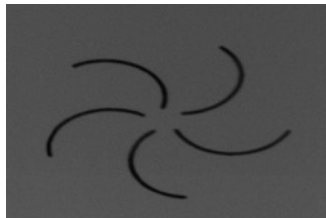
Japanese art of paper folding (Origami) and cutting (Kirigami)



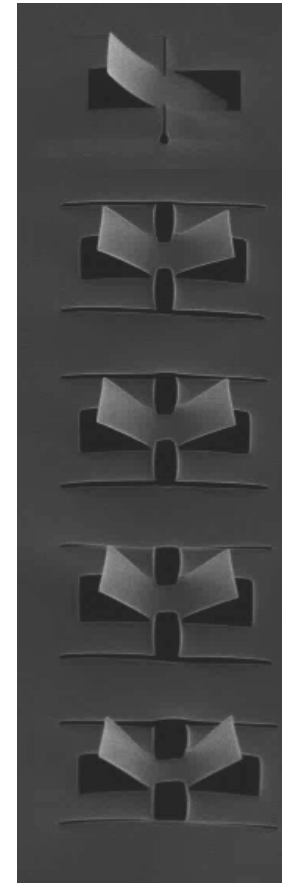
Powerful strategy to transform 2D layouts



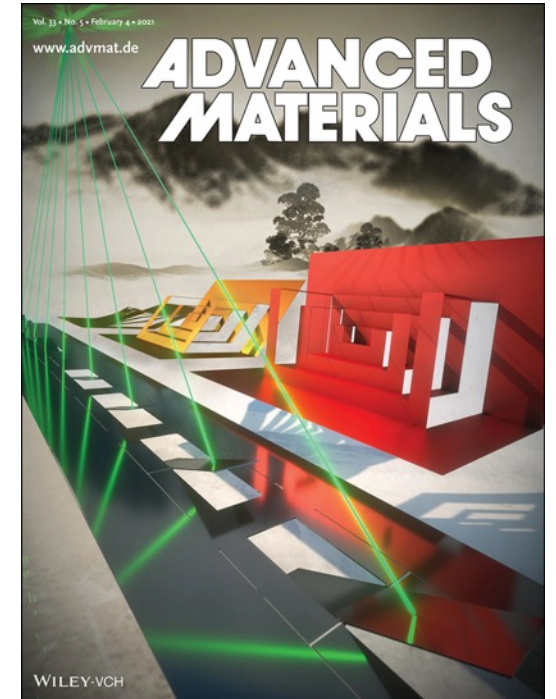
**Scale Invariant** 3D complex architectures



t = 100 nm



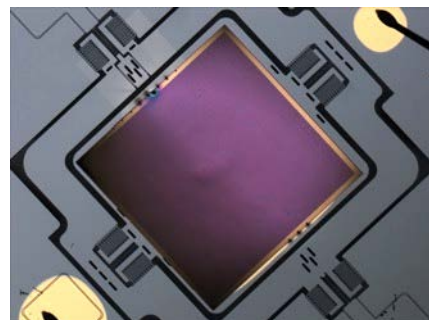
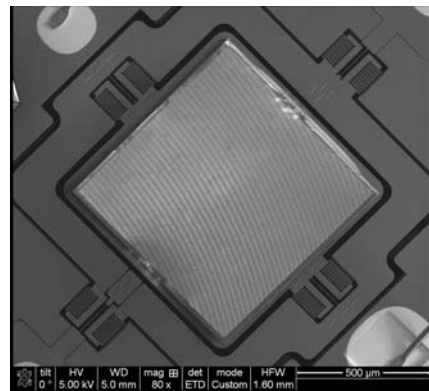
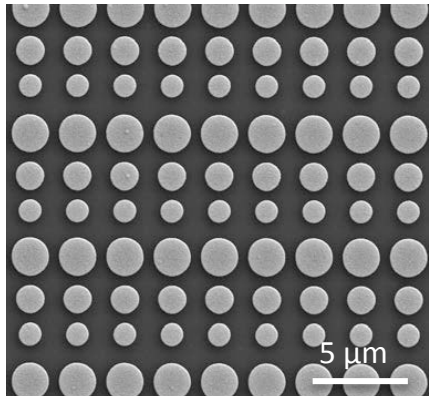
t = 50 nm



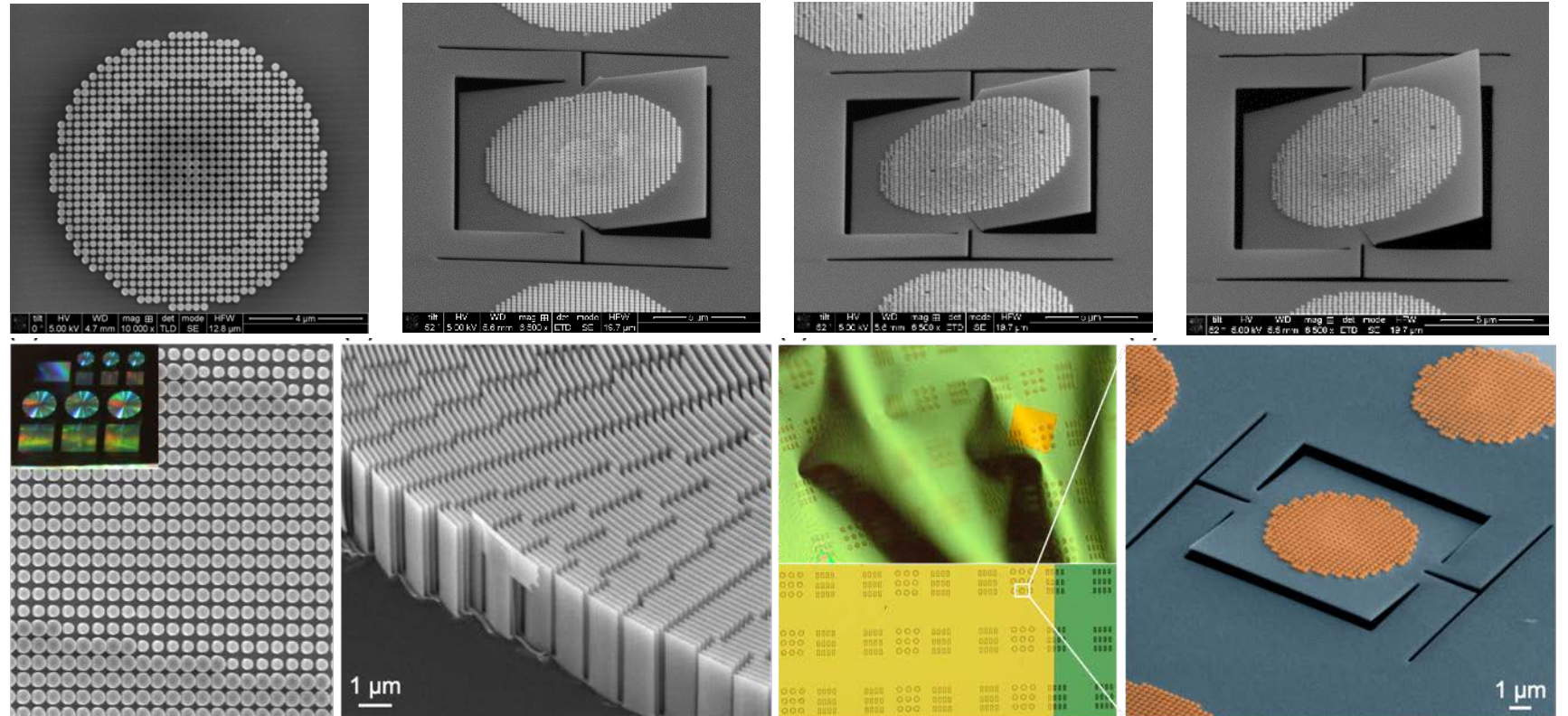
The most innovative applications of Origami/Kirigami engineering is the combination of structural and morphing capabilities that alters a device shape or enhances a material property.

# Kirigami-based metasurfaces

Incorporation of metasurfaces onto MEMS scanners



New methodology to fabricate complex 3D nanostructures: Reconfigurable Metasurfaces



New fabrication of complex and tunable 3D nanostructures

- Monolithic integration
- Van der Waals techniques
  - hybrid integration of materials
  - piezoelectric, 2D, metals, metasurfaces

Xu Zhang (CMU)  
Haogang Cai (NYU)



# Intelligent microscale systems: what's next?

- Integrating sensing/learning functions
- Passive or active shape & dynamics
- Energetics of communications at small scale
  - High and expensive
  - how much communication you need
  - is local communication enough
- Swarms of autonomous micromachines
  - Coordination
  - Emergent behavior

## Smart swarms

A simple model of interactions among self-propelled particles can realistically simulate the movement of flocks of birds, schools of fish, self-assembling proteins in the cell and many other forms of active matter.

### Low density: randomness

When individuals have few neighbours to compare themselves to, they mill about with no obvious pattern.

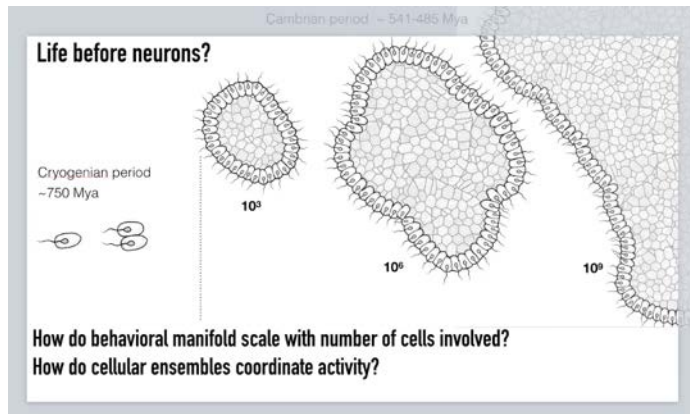


### Higher density: flocking

As the density increases, the group's motion becomes synchronized.

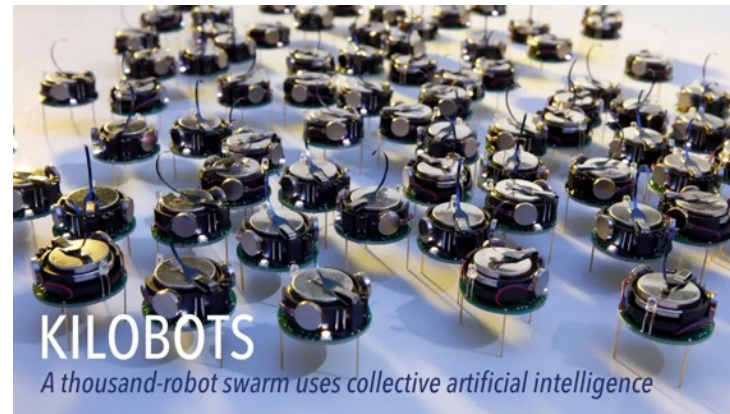


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## Manu Prakash (Stanford)

How does biological matter and body computation work?

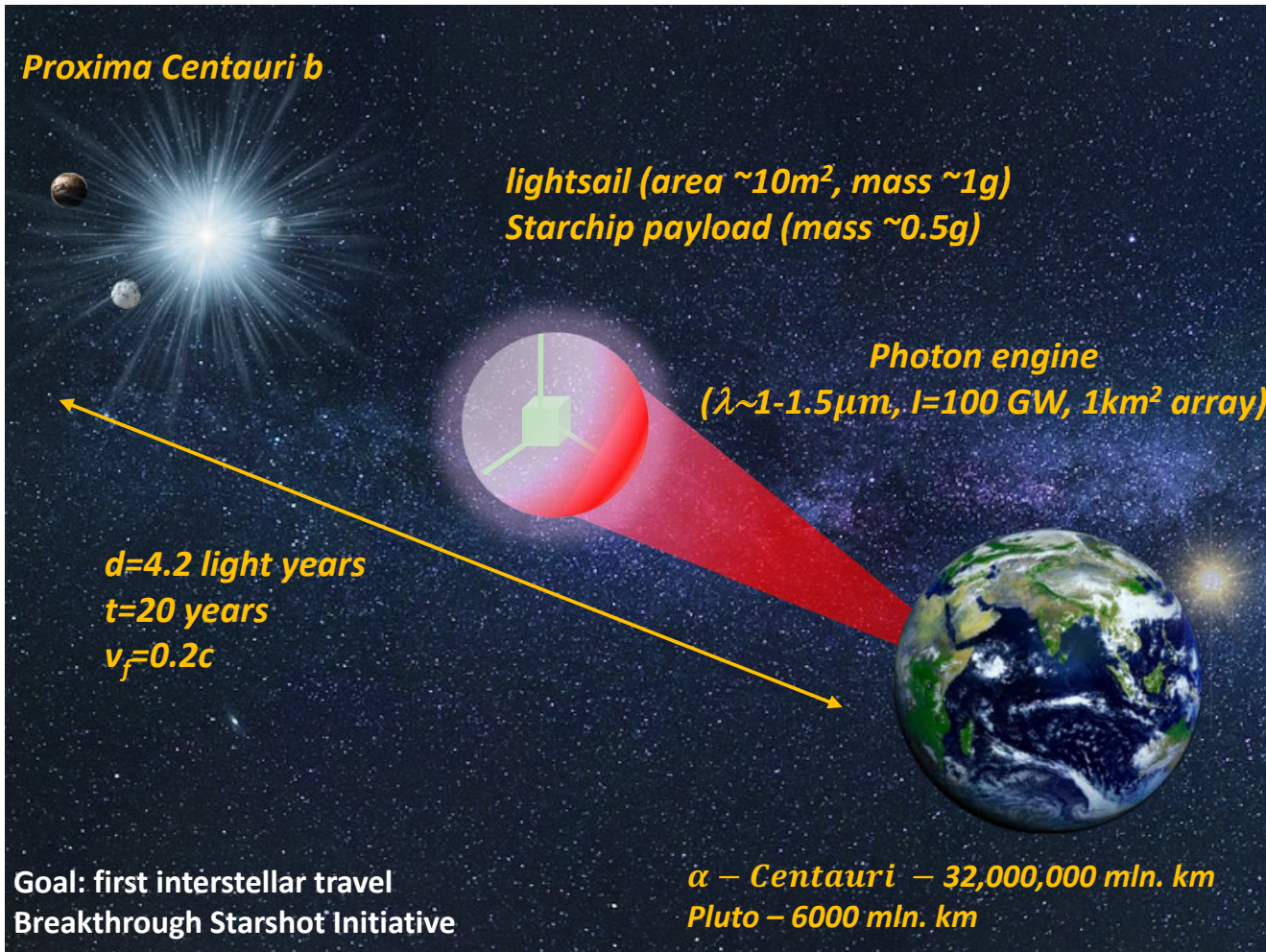


## Radhika Nagpal (Harvard)



# The Next Big Thing (?)

## Materials and structures for space exploration and settlement



nature  
materials

PERSPECTIVE

<https://doi.org/10.1038/s41563-018-0075-8>

## Materials challenges for the Starshot lightsail

Harry A. Atwater<sup>1\*</sup>, Artur R. Davoyan<sup>1</sup>, Ognjen Ilic<sup>1</sup>, Deep Jariwala<sup>1</sup>, Michelle C. Sherrott<sup>1</sup>, Cora M. Wentz<sup>2</sup>, William S. Whitney<sup>2</sup> and Joeson Wong<sup>1</sup>

The Starshot Breakthrough Initiative established in 2016 sets an audacious goal of sending a spacecraft beyond our Solar System to a neighbouring star within the next half-century. Its vision for an ultralight spacecraft that can be accelerated by laser radiation pressure from an Earth-based source to  $\sim 20\%$  of the speed of light demands the use of materials with extreme properties. Here we examine stringent criteria for the lightsail design and discuss fundamental materials challenges. We predict that major research advances in photonic design and materials science will enable us to define the pathways needed to realize laser-driven lightsails.

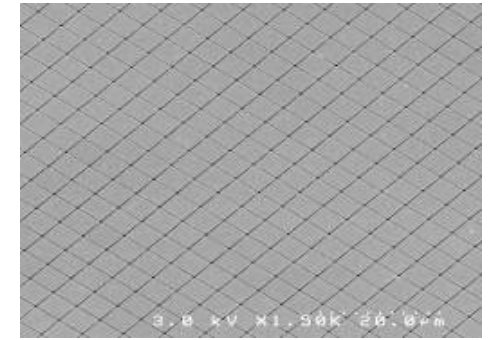
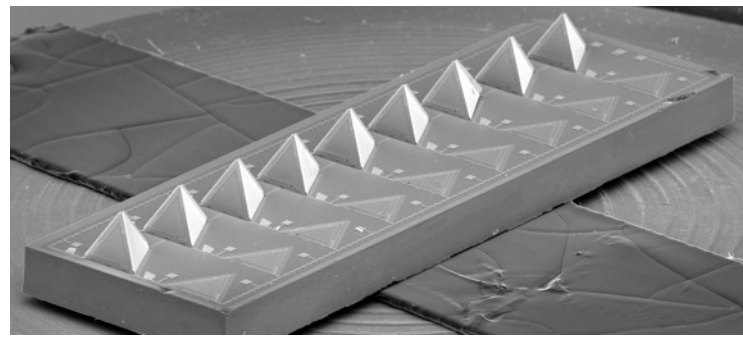
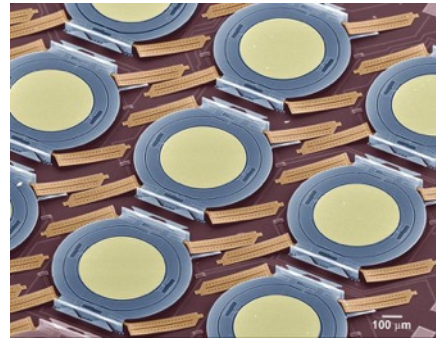
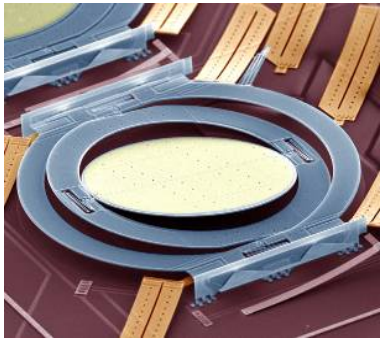
*In order to reach relativistic speeds, the Starshot lightsail should have an area of  $\sim 10\text{ m}^2$  and be kept to a mass of under  $\sim 1$  gram, which translates into an equivalent thickness of approximately 100 atomic layers. The design of the lightsail will therefore need to push the boundaries of materials science, photonic design and structural engineering to enable high performance with minimal mass.*

H. Atwater (Caltech)

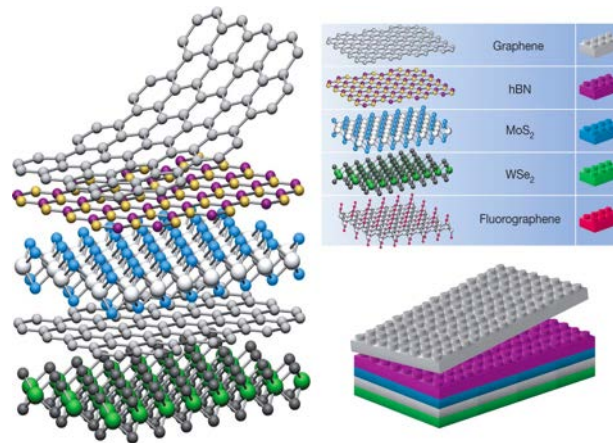
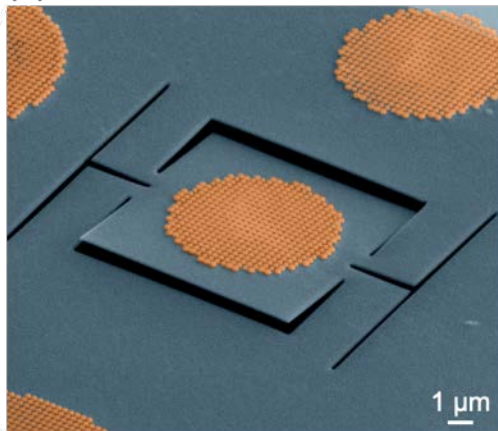
**The most innovative applications of Origami/Kirigami engineering is the combination of structural and morphing capabilities that enhances or alters a material characteristic**



# Conclusions



- Very large-scale integration of MEMS
  - Intelligent micro-systems



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